

A novel approach to H coupling measurements

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Based on arXiv:1401.0080

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CP3 - Université Catholique de Louvain



MINIWORKSHOP ON SCALAR SEARCH & STUDY

S3Be meeting

-

ULB Brussels

- January 23th 2014

Outline

- 1 Context & motivation
- 2 Laying out the strategy
- 3 Confronting it to new physics
- 4 Summary

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1 Context & motivation

2 Laying out the strategy

3 Confronting it to new physics

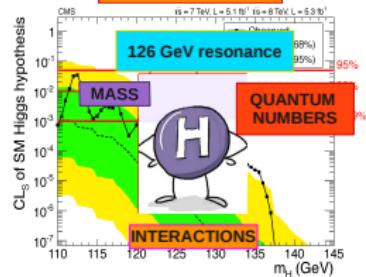
4 Summary

The context

One evidence



One program

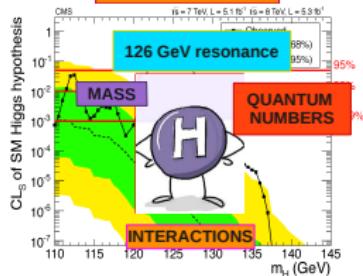


The context

One evidence



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Two prominent caveats

♠ Theoretical uncertainties

- Poorly defined : scale/scheme dependence, kinematic cuts, parton shower ...
- Not probabilistic \Rightarrow Not suitable for statistical treatment

♠ New Physics effects

- Overlayed with theory uncertainties
- Similar low-energy impact from manifold UV origin

The context



$$\mu_i^p \equiv \frac{\sigma_p \times BR_i}{\sigma_p \times BR_i^{\text{SM}}} = \left(\frac{\sigma_p}{\sigma_p^{\text{SM}}} \right) \left(\frac{\Gamma_i}{\Gamma_i^{\text{SM}}} \right) \left(\frac{\Gamma_{\text{H}}^{\text{SM}}}{\Gamma_{\text{H}}} \right) \mu_i^p \equiv 1 + \delta \mu_i^p$$

(K. & S.)

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- **recouple** them at any point later ?
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 Stage 0:

 statistical model

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CMS-NOTE-2011-005

- **Data sets**: $D_c = \{x_1 \dots x_{n_c}\}$ per disjoint category c
- **PDF**: $f(\vec{x}_c | H(\mu, \alpha))$ – signal strength μ – nuisance param. α
- **Expected signal**: $s_{cpd}(\vec{\alpha}) = L(\vec{\alpha}) \sigma_p^{\text{SM}}(\vec{\alpha}) \text{BR}_d^{\text{SM}}(\vec{\alpha}) \epsilon_{cpd}(\vec{\alpha})$
- **Expected number of events**: $\nu_c(\vec{\mu}, \vec{\alpha}) = \sum_{p,d} \mu_{pd} s_{cpd}(\vec{\alpha}) + b_c(\vec{\alpha})$
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$$L_{\text{full}}(\vec{\mu}, \vec{\alpha}) = \underbrace{\prod_{c \in \text{category}} \left[\text{Pois}(n_c | \nu_c(\vec{\mu}, \vec{\alpha})) \prod_{e=1}^{n_c} f_c(x_e | \vec{\mu}, \vec{\alpha}) \right]}_{\equiv L_{\text{main}}(\vec{\mu}, \vec{\alpha})} \underbrace{\prod_{i \in \text{syst}} f_i(a_i | \alpha_i)}_{\equiv L_{\text{constr}}(\vec{\alpha})} .$$

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$$\lambda(\vec{\mu}) = \frac{L(\vec{\mu}, \hat{\alpha})}{L(\hat{\mu}, \hat{\alpha})}$$

Cowan, Cranmer, Gross, Vitells ['11]

Laying out the strategy

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♣ effective signal strength & likelihood

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♣ The aim:

Infer $\vec{\mu} = \vec{\mu}(s_{cpd}, b_c)$

♣ The obstacle:

$s_{cpd} = s_{cpd}(\alpha), b_c = b_c(\alpha)$

♣ Key idea:

we fix $\alpha = \alpha_0$ & reabsorb α -dependence

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$$\nu_c(\vec{\mu}, \vec{\alpha}) = \sum_{p,d} \mu_{pd} s_{cpd}(\vec{\alpha}) + b_c(\vec{\alpha})$$



$$\sum_{p,d} \mu^{\text{eff}}_{cpd}(\vec{\mu}, \vec{\alpha}) s_{cpd}(\vec{\alpha}_0) + b_c(\vec{\alpha}_0)$$

$$L_{\text{eff}}(\vec{\mu}^{\text{eff}}) \equiv L_{\text{main}}(\vec{\mu} = \vec{\mu}^{\text{eff}}, \vec{\alpha} = \vec{\alpha}_0)$$

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We trade a shift in α by a shift in μ^{eff}

Laying out the strategy



Stage 2:



Reparametrization template

Laying out the strategy

◆ Stage 2:

◆ Reparametrization template

- ◆ Expected signal dependence w.r.t **uncertainties**

★ on total rates

$$s_{cpd}(\vec{\alpha}) = s_{cpd}(\vec{\alpha}_0) \left[1 + \sum_i \eta_{pi} (\alpha_i - \alpha_{0,i}) \right]$$

★ on background

$$b_c(\vec{\alpha}) = b_c(\vec{\alpha}_0) \left[1 + \sum_i \phi_{ci} (\alpha_i - \alpha_{0,i}) \right] \quad (\forall p, d)$$

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- ◆ Fiducial choice:

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- linear/non-linear in $[\mu, \alpha_i]$
- computable from L_{eff}
- sensitive to category-correlated effects:

[e.g. GGF uncertainty for VBF isolation]

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Laying out the strategy

Stage 3:

Reconstruction technique

Laying out the strategy

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Reconstruction technique

- Split Fisher matrix into **main measure** + **constraint terms**:

$$V_{ij}^{-1} \equiv \partial_i \partial_j L_{\text{full}}(\vec{\mu}, \vec{\alpha}) \rightarrow V_{\text{main}}^{-1} + V_{\text{constr.}}^{-1}$$

- Introduce the effective Fisher matrix:

$$V_{\text{eff}}^{-1} \equiv \partial_i \partial_j L_{\text{eff}}(\mu^{\text{eff}})$$

- Introduce the reparametrization:

Mapping:

$$\mu^{\text{eff}}(\vec{\mu}, \vec{\alpha})$$

Coefficients:

$$\{\eta_i, \phi_i\}$$

$$V_{\text{eff}}^{-1} = J^T V_{\text{eff}}^{-1} J$$

with

$$J = \frac{\partial \mu^{\text{eff}}(\mu, \alpha)}{\partial (\mu, \alpha)}$$

- Impose local covariance equivalence around $(\hat{\mu}, \hat{\alpha})$:

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LINEAR SYSTEM

Laying out the strategy

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η_i, ϕ_i

- ♦ Computational tools available at <http://github.com/svenkreiss/decouple>
- ♦ Analytical toy example available at <arXiv:1401.0080>

Laying out the strategy



Stage 4:



Recoupling the uncertainties

Laying out the strategy

♠ Stage 4:

♣ Recoupling the uncertainties

$$L_{\text{full}}(\vec{\mu}, \vec{\alpha}) \approx L_{\text{recouple}}(\vec{\mu}, \vec{\alpha}) \equiv L_{\text{eff}}(\vec{\mu}^{\text{eff}}(\vec{\mu}, \vec{\alpha})) \cdot L_{\text{constr}}(\vec{\alpha})$$

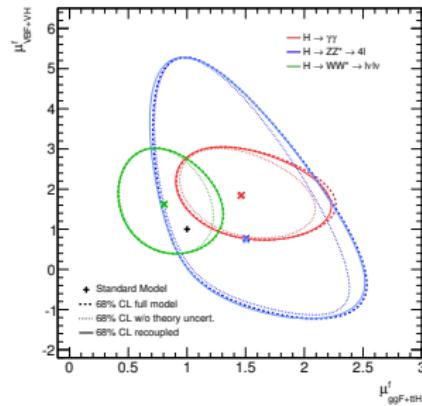
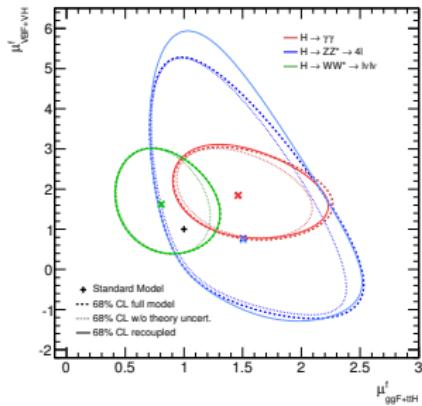
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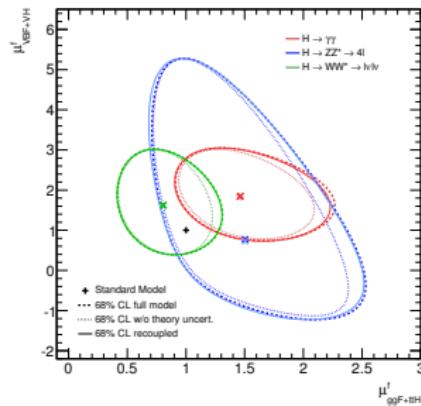
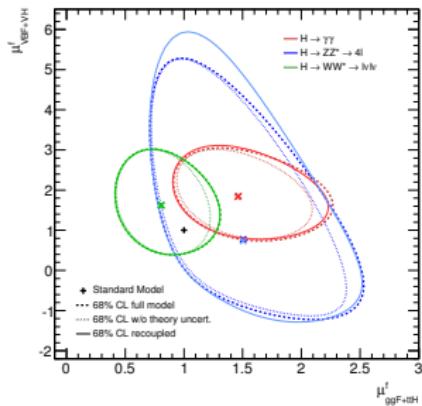
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- To be dealt with care: non-linearities in μ, α & category-weighted effects

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Theory uncertainties VS new physics effects

GEOMETRY

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UNCERTAINTIES



GEOMETRY

RECONSTRUCTING

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NEW PHYSICS



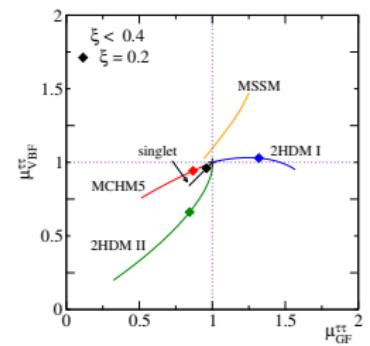
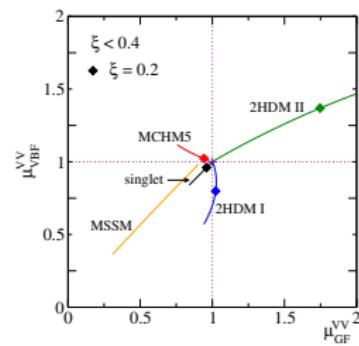
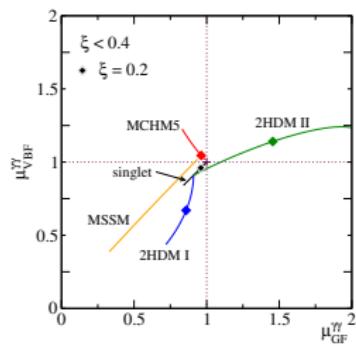
GEOMETRY



RECONSTRUCTING

DISENTANGLING

Theory uncertainties VS new physics effects



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UNCERTAINTIES

NEW PHYSICS



GEOMETRY

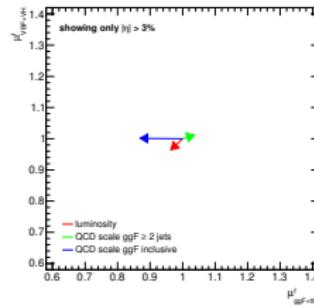
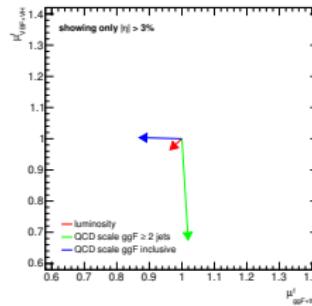
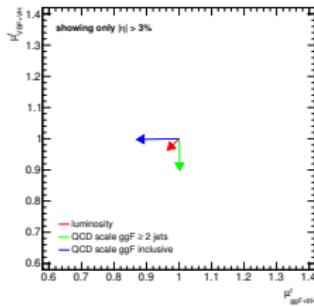


RECONSTRUCTING

DISENTANGLING



New physics effects neatly depart from theory uncertainties



Theory uncertainties VS new physics effects

Deviations from the SM

Theory uncertainties VS new physics effects

Deviations from the SM

SIZE

How large?

Theory uncertainties VS new physics effects

Deviations from the SM

SIZE

DIRECTION

How large?

How orthogonal?

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SIGNAL STRENGHT CORRELATIONS

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Robustness heuristic for new physics effects

$$R_i(\mu) = \frac{|\mu - 1|^2 |\partial_{\alpha_i} \mu^{\text{fix}}|}{(\mu - 1) (\partial_{\alpha_i} \mu^{\text{fix}})}$$

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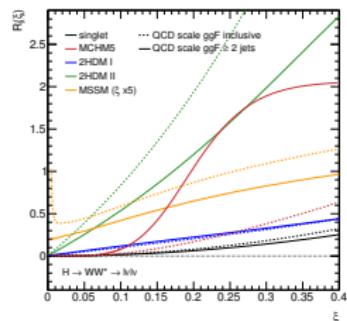
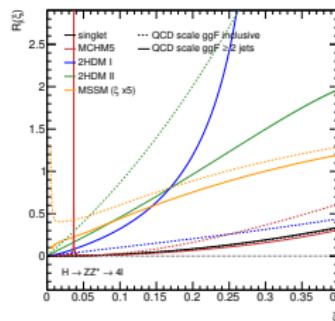
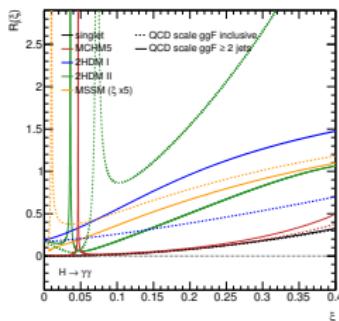
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$\xi \rightarrow 0$: model-independent SM-like limit

Outline

1 Context & motivation

2 Laying out the strategy

3 Confronting it to new physics

4 Summary

A novel approach to Higgs coupling measurements

A strategy based on

- ♠ One Purpose : decoupling(recoupling) uncertainties from(to) best-fit estimates
- ♠ Three key elements L^{eff} – $\mu^{\text{eff}}(\mu, \alpha)$ – reconstruction technique

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Allows to

- ♠ Recouple uncertainties at any point
 - Upgrade analyses with improved modelling and/or theory predictions
 - Reinsert *a priori* correlations in the systematics
 - Generate likelihood scans for benchmark models
 - Combine likelihoods consistently
- ♠ Interpret uncertainties & new physics effects *geometrically*
 - Intuitive visualization - correlated variations in the signal strength plane
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- ♣ Software & worked examples available at <http://github.com/svenkreiss/decouple>
- ♣ way broader applications foreseen !